

DENON

Hi Fi Component

SERVICE MANUAL

FULLY AUTOMATIC

DIRECT DRIVE TURNTABLE SYSTEM

MODEL DP-23F SERIES
(EUROPEAN MODELS)




NIPPON COLUMBIA CO., LTD.

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WARNING:

1. Component parts

Parts marked with  and/or shading in this service manual have special characteristics important to safety. Be sure to use the specified parts for replacement.

2. Leakage current

Before returning the appliance to customer, test the leakage current when the power plug is connected. Use a calibrated (with an error of not more than 5%) leakage current tester and measure the leakage current from any exposed metal to the earth ground. Reverse the power plug polarity and test the above again.

Any current measured **MUST NOT EXCEED 0.5 milliamps**. Corrective measure must be taken if it exceeds the limit.

FEATURES

Silent, fully automatic operations with the use of a microprocessor controlled contactless servo tonearm.

An innovative microprocessor controlled, contactless servo tonearm ensures safe, easy to use automatic operations with little loss in sound quality.

Low mass straight arm

This arm is fully capable of maximizing the performance of high compliance cartridges with outstanding tracing ability. Even with the newest, high grade records, its tracing ability is outstanding.

DENON Quartz

The turntable speed is controlled by the "DENON Quartz" which is the combination of the "High Precision Magnetic Pulse Detection Method", the most sophisticated method of FG detection, and the "Quartz Lock".

SPECIFICATIONS

Phonomotor section

Drive system:	Servo controlled direct drive
Turntable speeds:	33-1/3, 45 rpm
Wow & flutter:	Below 0.02% wrms (servo system) Below 0.03% wrms (JIS)
S/N ratio:	Over 75 dB (DIN-B)
Rise time:	Normal speed within 2 seconds (at 33-1/3 rpm)
Platter:	Aluminum die-cast; 300 mm diameter
Motor:	Linear drive motor
Speed control system:	Speed servo by frequency detection, phase servo control
Speed deviation:	Below 0.002%
Load characteristics:	0% (80 g stylus force; outermost groove)

General

Power supply:	50~60 Hz, Voltage is shown on rating label
Power consumption:	7 W
Dimensions:	105 x 434 x 360 mm (H x W x D)
Weight:	Approximately 5 kg

Tonearm section

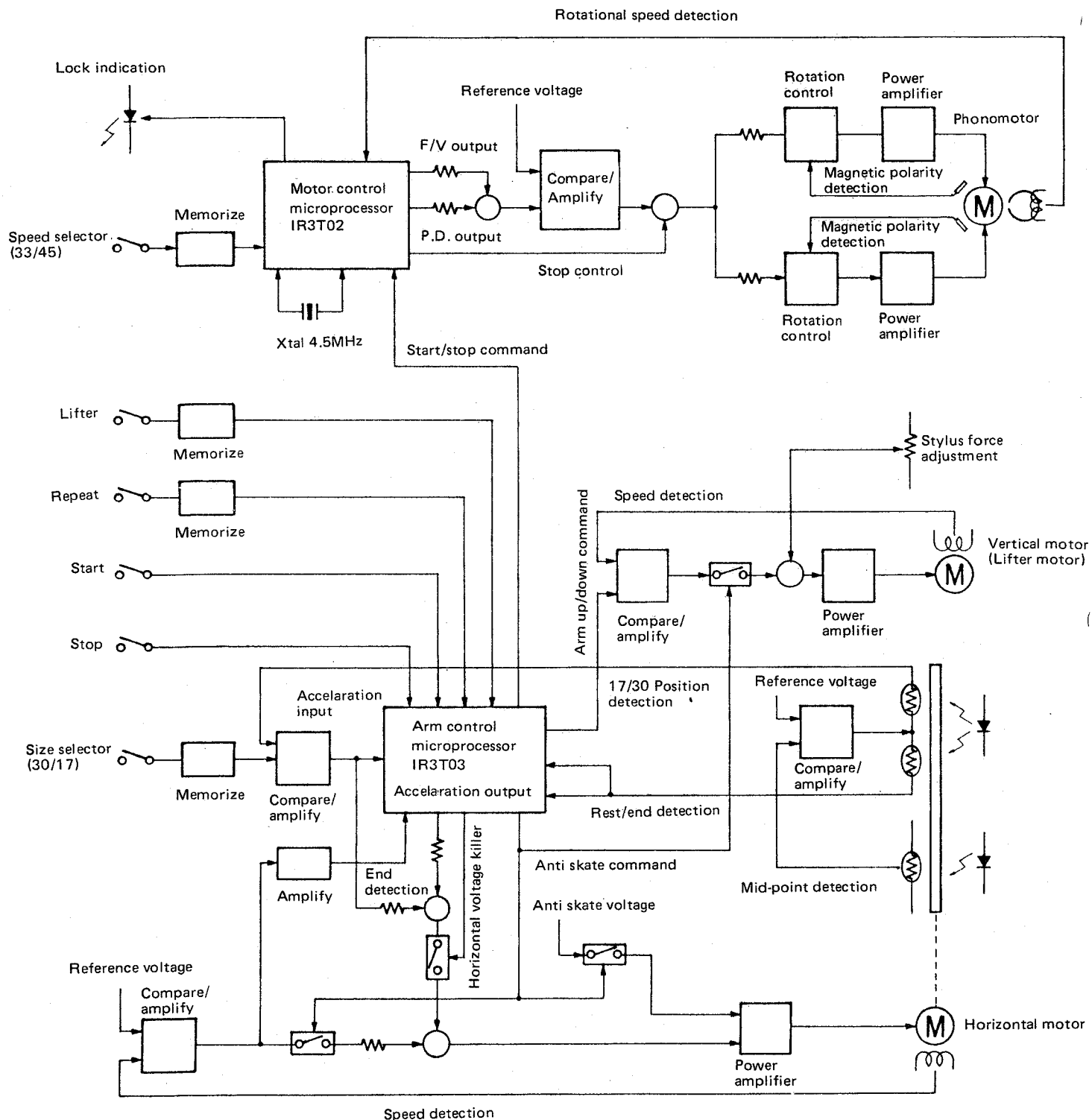
Arm type:	Dynamically balance, semi-integrated straight arm
Effective length:	220 mm
Overhang:	16 mm
Tracking error:	Within 3°
Automatic mechanism:	Electronically controlled, fully automatic
Adjustable stylus force range:	0~3.0 g (1 scale=0.1 g)
Suitable cartridge weight range:	Approximately 4.0~9.0 g (including screws, nuts)


Cartridge section (Only for those models with attached cartridge)

DL-80MC	
Type:	Moving coil (MC)
Output voltage:	1.6 mV
Frequency response:	20~45 kHz
Stylus force:	1.8±0.3 g

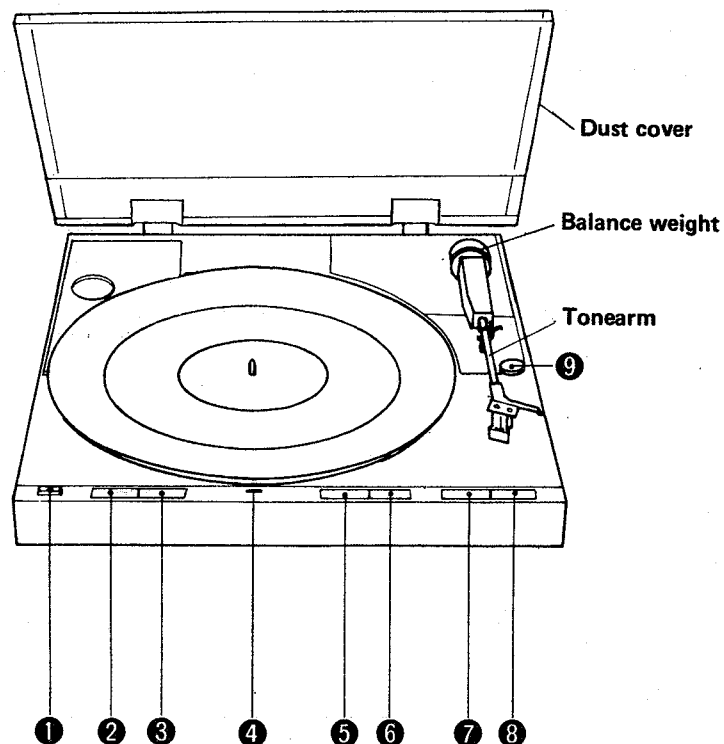
Above specifications and outward appearance may be altered in future for improvement

BLOCK DIAGRAM



Note:  indicates an analog switch.

PART NAMES AND FUNCTION



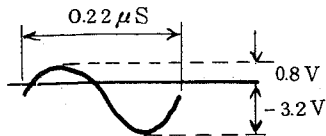
- ① POWER (Power switch)**
 This switch turns the power supply on (—) and off (⏏). When turning the power off, always return the tonearm to the arm rest and hold it in place with the clamp.
- ② SIZE (Record size selector switch)**
 Set to the size of record to be played.
 30 cm records "30" (lamp lit)
 17 cm records "17" (lamp lit)
- ③ SPEED (Speed selector switch)**
 Set to the desired record speed.
 33-1/3 rpm records "33" (lamp lit)
 45 rpm records "45" (lamp lit)
- ④ LOCK (Lock indicator)**
 When the power is turned on, the lamp will light up. During play, the lamp will flicker until the proper turntable speed is reached. Once the proper speed is obtained, the lamp will, again, stay lit.
- ⑤ REPEAT (Repeat switch)**
 When playing the records repeatedly, switch it on (lamp lit).
- ⑥ ARM LIFTER (Arm lifter switch)**
 This switch is used to raise and lower the arm during play or when playing the records manually. The lamp is lit when arm is up.
- ⑦ START (Start switch)**
 Press this switch when starting the records automatically.
- ⑧ STOP (Stop switch)**
 Press this switch when stopping the record during play.
- ⑨ STYLUS FORCE (Stylus force adjustment knob)**
 This knob is used to adjust the stylus force.

EXPLANATION OF THE MICROPROCESSOR

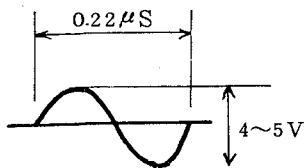
• Motor Control IC ... IR3T02 (at standard revolution of 33 rpm)

The numbers on the left hand side indicates the terminal number.

2. 4.5MHz OSC



3. 4.5MHz OSC



4. rpm selector

H: 45 rpm
L: 33 rpm

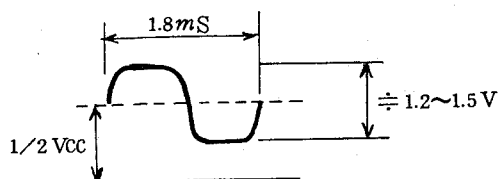
5. power source input

V_{cc} : 5V \pm 0.5V

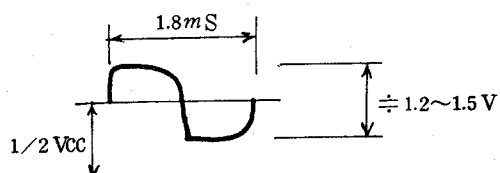
6. FG I bypass terminal

$E6 \div \frac{1}{2}V_{cc}$

7. FG I lowpass terminal



8. FG I output



9. FG I inverse input

The gain set element is connected.
 $E9 \div \frac{1}{2}V_{cc}$

10. FG I non-inverse input

10mVpp \sim 100mVpp
 $E10 \div \frac{1}{2}V_{cc}$

14. ground terminal

15. F/V output

slower than normal revolution: 2 \sim 4.5V
normal revolution: $\div 2V$

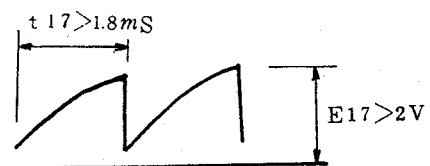
faster than normal revolution: 0 \sim 2V

16. F/V hold terminal

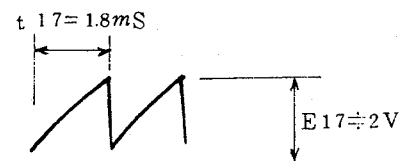
same as terminal 15

17. F/V triangular wave

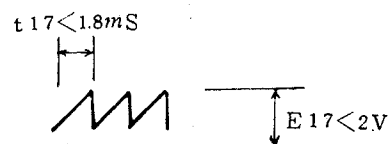
slower than normal revolution



normal revolution



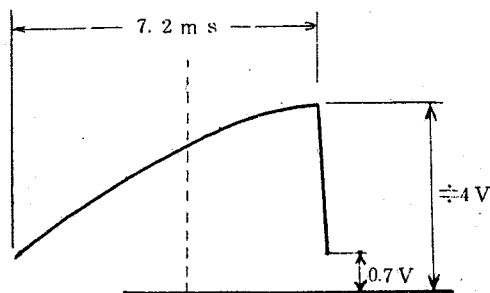
faster than normal revolution



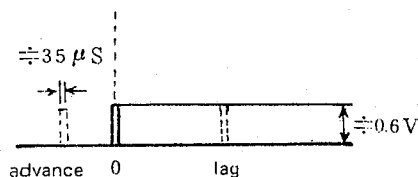
18. timing pulse width-set terminal

$E18 \approx 0.6V$

19. PD triangular wave



20. sample pulse monitor terminal



Monitor for phase-lock:

Waveforms at Pins 19 and 20 to be observed with a dual trace oscilloscope when GND is common. (See "Lock adjustment.")

21. PD hold terminal

slow phase: 2 ~ 4V
normal phase: $\approx 2V$
advanced phase: 1 ~ 3V

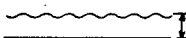
22. PD output

same as terminal 21

23. Lock detector time set terminal

during lock: 0.6V
lock disengaged: 0V

25. Revolution detector

during revolution:  $\div 4V$

stop: 0V

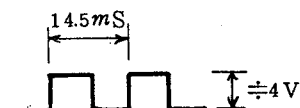
26. START/STOP terminal

H \rightarrow START
L \rightarrow STOP

28. Lock indicator

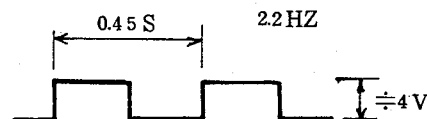
during lock (LED lit dimly)

69HZ



stop (LED lit)

during transition . . (LED flashes)



• Arm Control IC IR3T03

The numbers on the left side indicates the terminal number of the IR3T03.

1. Acceleration input

Except for the matching range of the lead-in detector ($E7 \leq |\pm 0.6V|$), it will recognize the situation and control the acceleration during automatic tonearm operation.

2. Acceleration output

$E1 \leq |\pm 2.37V \pm 0.1V|$ open (will not control the acceleration within the matching range)

$E1 \geq |\pm 2.3V \pm 0.1V|$ $E2 \approx \pm 3.95V$

-3.95V: will accelerate toward the inside from rest.

+3.95V: will accelerate toward rest from the inside.

3. UP/DOWN selection of the arm lifter

When $E9$ is H, the control output for lifting the arm will be made at $E3 \approx -V_{cc}$.

When $E9$ is L, the control output for lowering the arm will be made at $E3 \approx +V_{cc}$.

4. Detection of the rest position

$E4 \leq -2.64V$ will be recognized as the arm being at rest.

5. Detection of the END position

When $E5 \geq 2.64V$, it will be recognized to be within the END detection range.

$E5 \geq 2.64V$ when the stylus tip nears the last sections of the sound groove.

6. End control

Whithin the END detection range of 5 (above), ($E5 \geq 2.64V$), the arm will be returned by the END control when $E6 \geq 0.23V$.

$E5 \geq 0.23V$ when the stylus tip moves into the lead-out groove and the arm moves fast.

7. Matching input

$E7 \leq |\pm 0.6V|$ will be recognized as the match range for lead-in.

8. Drive output

Connect to GND.

9. UP control output

When the lifter is in the UP position during automatic arm operations or when the UP signal is sent by pressing the arm lifter button, pin 9 will be at H level.

$E9H \approx 4V$

$E9L \approx 0V$

10. DOWN time constant

To ensure that the arm is lowered completely before proceeding to the next movement, a resistor between pins 9 and 10 and a capacitor on pin 10 has a preset discharge time constant which is somewhat longer than the time required for the arm to be lowered. Thus, when pin 9 becomes L ($E9L \approx 0V$), and the fixed amount of time elapses, the arm will be recognized to be DOWN as soon as $E10 < 2V$.

11. ANT (Anti-skating) control

When $E10 < 2V$, then $E11 \approx -4V$ will be the control output needed for the anti-skating to be engaged.

When $E10 \geq 2V$, then $E11 \approx +4V$ will be the control output needed for the anti-skating to be disengaged.

12. Negative power source

Supplies -5V.

14. SUB (substratum)

To prevent any interference from the inner elements of the LSI, the substratum terminal is connected to the unregulated side of the negative power source, since it has the lowest electric potential.

15. GND

Standard zero electric potential is the GND.

17. Return control

When the stop command is given, or when the repeat is disengaged and the END is detected ($E6 \geq 0.23V$), a control signal output ($E17H > 4V$) is made to return the arm to rest.

$E17H > 4V$

$E17L$: release

18. Horizontal drive control

When the arm is in resting position, or when the arm reaches the lead-in position during automatic play, and comes into the matching range ($E7 \leq |\pm 0.6V|$), a control signal output ($E18H \approx 4V$) is made to stop the horizontal motion of the arm.

19. Initial set

This is the preparation time setting terminal when the power source is turned on. The resistor in the LSI and the outer capacitor will set the charge time constant and carry out the initial set.

20. LCTD (Located) time constant

The LSI and its outer circuits will set the LCTD time constant to improve the detection accuracy of the lead-in position and the arm rest position.

E20H \approx 1.2V A few moments after the arm reaches the range of detection, in other words, after the set LCTD time constant elapses, it will become H level, where it is memorized immediately and then reset to the L level.

E20L \approx 0V Before and after detection, it will become L level.

21. Turntable (T/T) Drive Control

E21L \approx 0V the turntable stops

E21H release the turntable rotates

(refer to the operational explanations for pin 22)

22. Turntable (T/T) Start Position

This terminal establishes the turntable start position. The turntable will start when the arm separates from the arm rest and pin 22 is released, under manual and auto modes.

23. Start

Will start automatically at the GND level.

24. Auto stop

Will stop automatically at the GND level.

25. Lifter

Will raise the lifter automatically at the GND level.

26. Repeat

Will engage the repeat automatically at the GND level.

27. UP SW

An UP time constant circuit is used so that when the lifter is in the UP condition, this terminal is released and becomes H level; and at other times, it becomes GND level.

With this unit, the arm will start to move approximately two seconds after the UP command.

28. Positive power supply

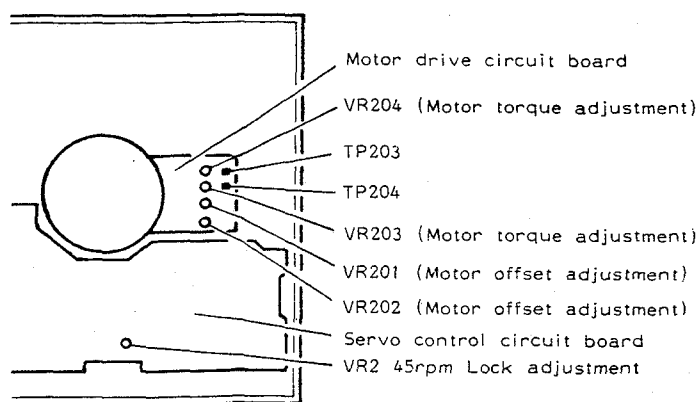
Supplies +5V.

ADJUSTMENT METHOD

* Prepare a two-channel oscilloscope for the measuring instrument.

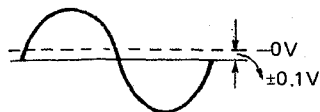
• Adjusting the Phonomotor Section

* Measure, using the wrapping terminal number 8 of the motor drive circuit board as the ground reference point when adjusting the motor OP amp. voltage offset and the motor torque.



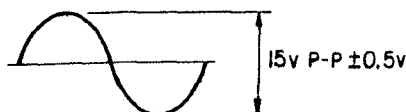
1. Adjusting the motor amp. offset voltage

- 1) Fix the tonearm to the arm rest and connect the oscilloscope to TP 203 and 204.
- 2) Rotating the turntable by hand, adjust the center of amplitude at TP 203 to $0 \pm 0.1V$ by turning VR 201.
- 3) Following the preceding directions adjust to $0 \pm 0.1V$ by turning VR 202 for TP 204.



2. Adjusting the motor torque

- 1) Leave the oscilloscope connections as they were for the motor OP amp. voltage offset adjustments.
- 2) Take the turntable off the main body; move the tonearm close to the speed detection head and rotate the phonomotor at a fast speed.
(Note) Be very cautious as not to damage the cartridge during this procedure.
- 3) For T.P. 203, rotate VR 203 and adjust to $15VP-P \pm 0.5V$.
- 4) For T.P. 204, rotate VR 204 and adjust to $15VP-P \pm 0.5V$.



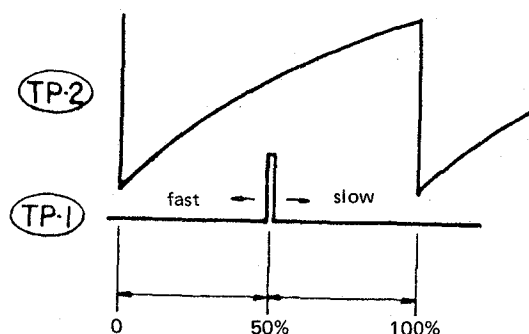
3. Adjusting the head gap

Adjust, so that the gap between the turntable magnetic coating surface and the detection head is 0.18 mm.

4. Lock adjustments for 45 rpm

From hereafter, the earth reference point of the measuring instrument should be connected to wrapping terminal 35 of the servo control circuit board.

- 1) Connect the two-channel oscilloscope to T.P. 1 and T.P. 2.
- 2) Set the speed selector to 45 rpm.
- 3) Take the arm off the arm rest and move it toward the turntable to rotate the phonomotor.
- 4) Adjust VR2 so that the pulse form T.P. 1 is positioned to 50% of the triangular wave length from T.P. 2.

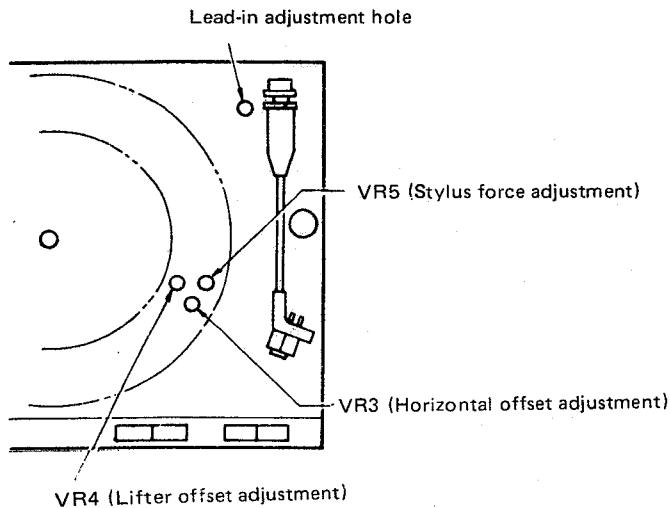


5. Lock adjustments for 33 rpm

- 1) Connect the oscilloscope in the same manner as the 45 rpm lock adjustments. Set the speed selector to 33 rpm.
- 2) Make sure that the sampling pulse positions between 40% and 80% of the triangular wave length.

Note: Phase lock position for 33rpm is fixed (relative to 45rpm) by R113 (metal film resistor).

● Adjusting the Arm Control Section



1. Adjusting the horizontal OP amp. offset voltage

- 1) Fix the tonearm to the armrest and connect the oscilloscope to T.P. 3.
- 2) Set the lifter switch to the UP condition.
- 3) Turn VR3 and adjust to $0V \pm 0.01V$.

2. Adjusting the lifter OP amp. offset voltage

- 1) Fix the tonearm to the armrest and connect the oscilloscope to T.P. 4.
- 2) Set the lifter switch to the DOWN condition.
- 3) Turn VR4 and adjust to $-1V \pm 0.1V$.

3. Adjusting the stylus force

- 1) Turn the power supply switch OFF.
- 2) Take the arm off the armrest. Rotate the balance weight so that the tonearm becomes parallel to the turntable surface when let go.
- 3) Return the arm to the armrest and turn the power supply switch ON.
- 4) Wait five seconds after the arm has lowered. Place the cartridge stylus tip onto a stylus force gauge and set the stylus force adjustment knob to 1.5 g.
(Note) At this time, the stylus tip height should be adjusted so that it is about the same height as during play.
- 5) Turn VR5 and adjust, so that the stylus force gauge reads 1.5 g.

4. Adjusting the 30 cm lead-in position

- 1) Place a 30 cm record on the turntable and set the record size selector switch to "30".
(Note) Keep the bottom cover closed.

- 2) Move the arm so that the stylus tip is at approximately the 30 cm lead-in position. Insert a small flat-headed screwdriver into the lead-in adjustment hole; move the arm back and forth and fit the screw driver into the groove of the cam inside gently.

- 3) After turning the screwdriver, pull it out. Press the start switch and adjust so that the stylus position stops at the 30 cm lead-in position.

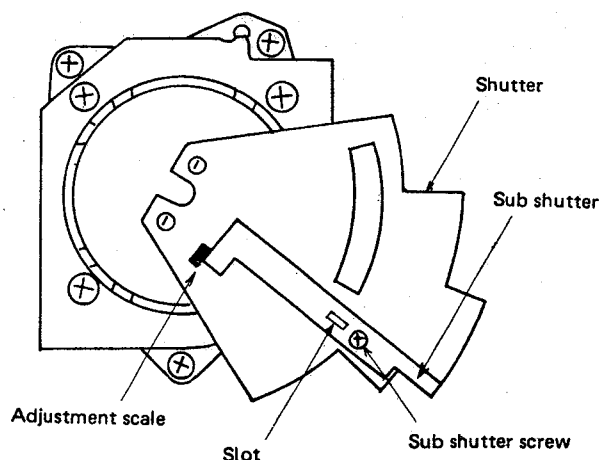
(Note) The 30 cm lead-in adjustments cannot be performed unless the stylus tip position is approximately in the 30 cm lead-in position. In addition, if the screwdriver is left inserted, the arm will not move.

5. Adjusting the 17 cm lead-in position

Adjust as necessary, such as when parts of the sensor section have been replaced.

However, the following procedures should only be used when a discrepancy is found for the 17 cm lead-in position, after the 30 cm lead-in position has been adjusted.

- 1) Set the record size selector to 17 cm.
- 2) By continuously pressing the start switch, the arm will move over and stop. At this time, check how many millimeters, toward the inside or outside, the stylus tip deviates from the required 17 cm lead-in position.
- 3) Take off the bottom cover of the cabinet and check the adjustment scale position of the shutter. (One adjustment scale corresponds to a stylus tip movement of 5 mm.)
- 4) Untighten the screw holding the sub shutter and place a small screwdriver into the slot of the shutter. When the stylus position is toward the inside, compared to the required position, move the sub shutter toward the right of the scale; when the stylus position is toward the outside, move the sub shutter toward the left. When completed, tentatively tighten the screw holding the sub shutter.
- 5) After the adjustments are made, press the start switch and check whether or not the stylus stops at the 17 cm lead-in position.
- 6) If the stylus stops at the required position, then tighten the sub shutter screw.



PARTS LIST OF EXPLODED VIEW

Ref. No.	Part No.	Part Name	Remarks
1	4730356017	3x12 CBRTS (2)	
2	4751106042	WASHER	
3	1048066018	INSULATOR ASS'Y	
4	4730306038	3x12 CBRTS (1) BKN	
5	1058085005	BOTTOM COVER ASS'Y	
6	4370306012	3x12 CBRTS (1)	
7	KU-440	SERVO CONTROL UNIT	81A, 81B, 81C, 81D, 81E, 81F
8	1138136117	SIZE KNOB	BLACK
	1138136104	SIZE KNOB	GOLD
9	1138135118	SPEED KNOB	BLACK
	1138135105	SPEED KNOB	GOLD
10	1138137116	REPEAT KNOB	BLACK
	1138137103	REPEAT KNOB	GOLD
11	1138138115	LIFTER KNOB	BLACK
	1138138102	LIFTER KNOB	GOLD
12	1138139114	START KNOB	BLACK
	1138139101	START KNOB	GOLD
13	1138140116	STOP KNOB	BLACK
	1138140103	STOP KNOB	GOLD
14	4618113000	SPRING PLATE	
15	4713808003	3x25 CBS	
16	4731806003	3x20 CPTS (1)	
17	FG-286	MOTOR ASS'Y	
18	4730304014	3x8 CBRTS (1)	
19	4418846001	WASHER	
20	4428163101	HEAD SUPPORT	
21	3918425004	MAGNETIC HEAD	
22	4700009019	3x6 CPS W	
23	2118024002	V16V15KB502	
24	1120523039	VOLUME KNOB	BLACK
	1120523026	VOLUME KNOB	GOLD
25	1038206516	CABINET	BLACK
	1038206574	CABINET	GOLD
26	4418863000	FRICTION SHEET	
27	4730205016	2.6x10 CPTS (1)	
28	2123180003	BUSH SWITCH	
29	1138146013	KNOB	BLACK
	1138146000	KNOB	GOLD
30	2033642103	OUTPUT CORD ASS'Y	
31	2052002031	AC CORD	
32	4730309019	3x16 CBRTS (1)	
33	4620027003	RUBBER BUSH	
34	2030150009	WIRE CONNECTOR	
35	2330059005	POWER TRANS	
36	4711810019	2x3 CPS	
37	4338243001	SUB SHUTTER	
38	4712303017	3x6 CFS	
39	4711303018	3x6 CPS	
40	4751003006	3 W	
41	4438545201	COLLAR	
42	4338261009	SHUTTER	
43	4638225004	SPRING	
44	3418025205	MAGNET ASS'Y	
45	4761003009	3 E-RING	
46	4751005004	4 W	
47	3158451003	FRICTION WASHER	
48	4248019202	ADJUST CAM	
49	2398013215	COIL ASS'Y	
50	4338181008	YOKE (A) GENE ASS'Y	
51	4744102037	3x3 SS	
52	4418815100	ARM PLATE	
53	3158744105	BALANCE WEIGHT	
54	3150337002	MAIN BODY ASS'Y	
55	3159008002	ARM REST ASS'Y	
56	FSC00903	SHELL SCREW	

Ref. No.	Part No.	Part Name	Remarks
57	DL-80MC	CARTRIDGE UNIT	
58	FPU0379J	SHELL WASHER	
59	FSC0089	SHELL NUT	
60	4628023009	BUSHING	
61	1468139208	DUST COVER	
62	4018041015	HINGE	
63	4218288005	RUBBER SHEET	
64	4218312607	RECORDED TURNTABLE	
65	3158751004	SHELL SCREW	
69	3158966006	HEAD SHELL ASS'Y	
70	3150336003	TONE ARM ASS'Y	


CARTON CASE GROUP

Ref. No.	Part No.	Part Name	Remarks
	5018252133	CARTON CASE ASS'Y	
	5028074000	PACKING ASS'Y	
	5058092010	LAMINATE ENVELOPE	
	5058017011	ENVELOPE	60x260x0.03t
	5058006006	ENVELOPE	60x100x0.03t
	5058023018	ENVELOPE	350x640x0.05t

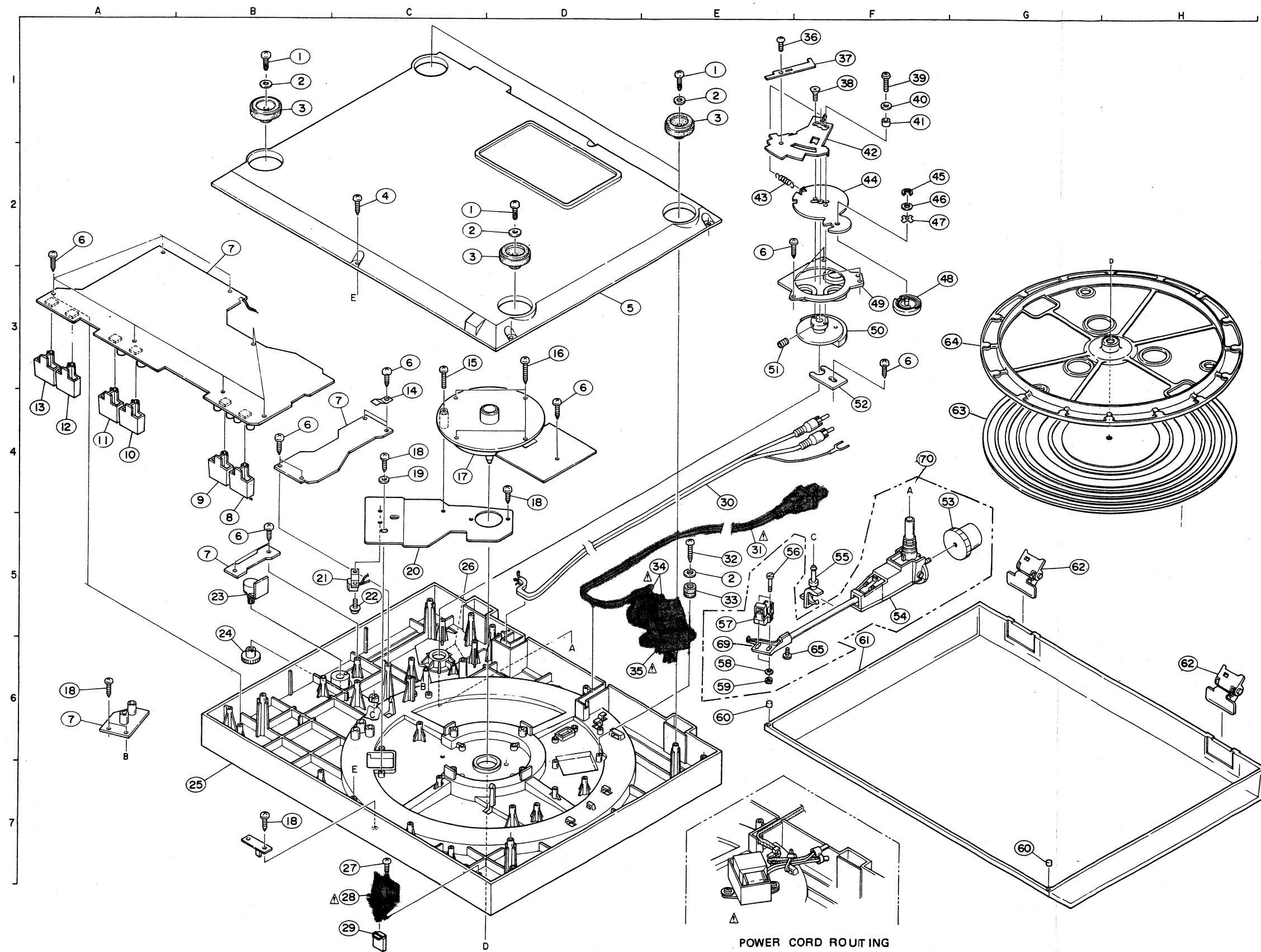
ACCESSORIES GROUP

Ref. No.	Part No.	Part Name	Remarks
63	5298006002	45 ADAPTOR	
	4218288005	RUBBER SHEET	
	5111491008	INSTRUCTION MANUAL	
	5111492007	SWEDISH INST. MANUAL	
	5111546005	SPANISH INST. MANUAL	

WARNING:

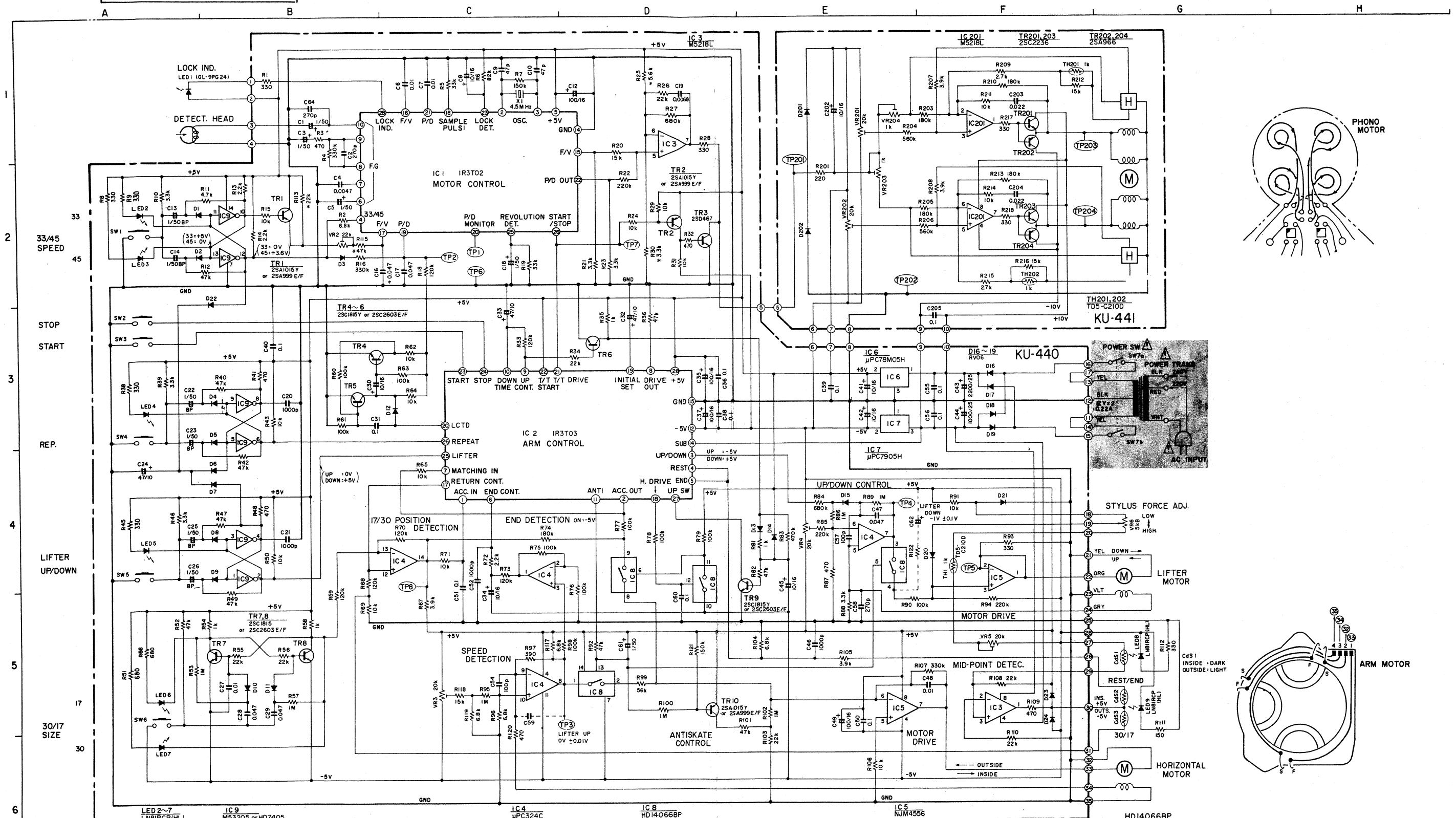
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EXPLODED VIEW OF MAIN PARTS

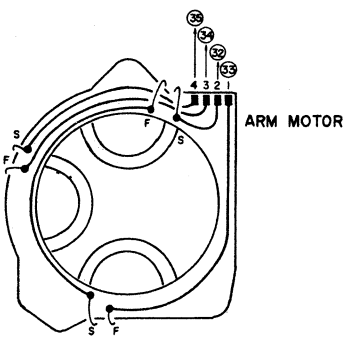
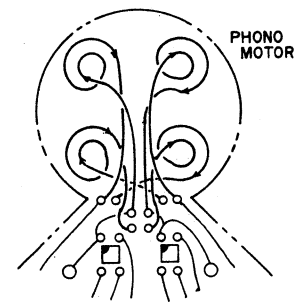
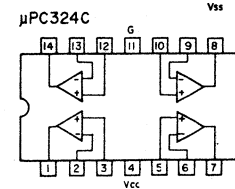
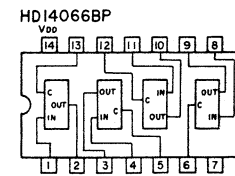
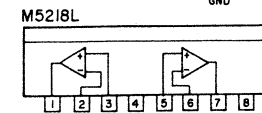
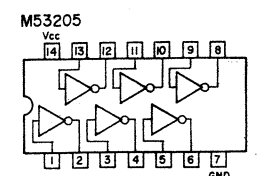
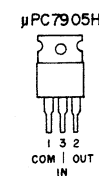
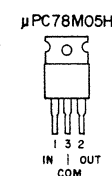
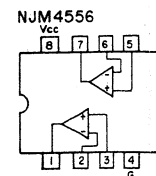


POWER CORD ROUTING

SCHEMATIC DIAGRAM

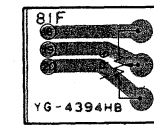
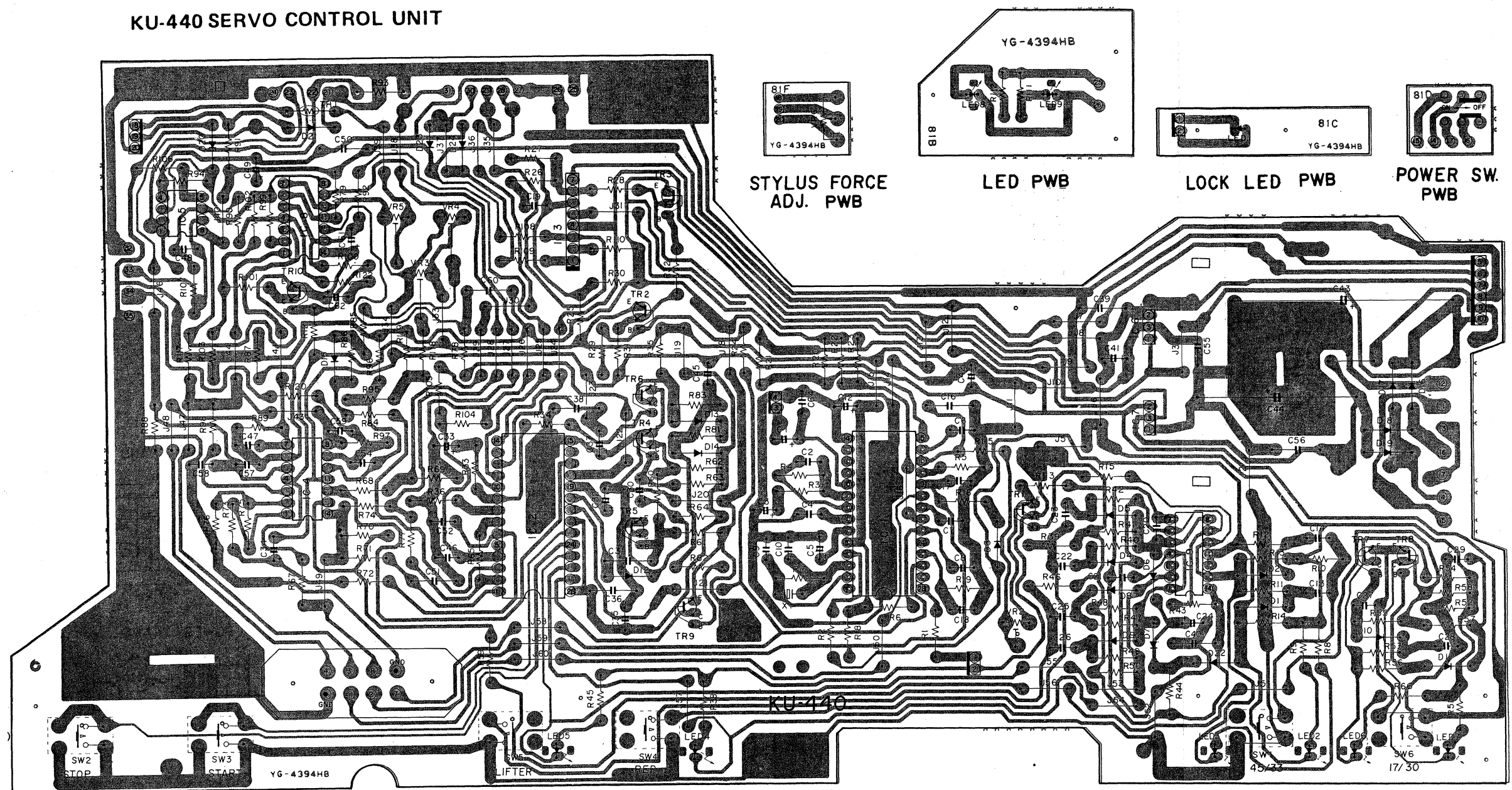


- Note:**
- Resistance shall be 1/4W unless otherwise specified and the unit is Ω .
 - The unit of capacitor is μF , P is pF unless otherwise specified.
 - Parts marked with Δ are of importance in respect to the safety, use the specified type without fail.
 - The voltage values are measured using the circuit tester (DC 100 k Ω /V).
 - This circuit diagram shows the basic circuit. It is subject to change for the purpose of improvement.

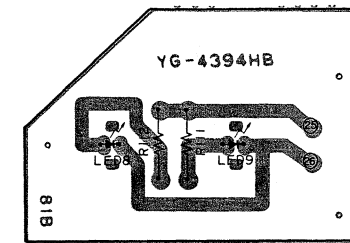


PRINTED WIRING BOARD

KU-440 SERVO CONTROL UNIT



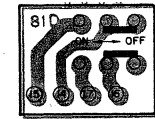
STYLUS FORCE
ADJ. PWB



LED PWB

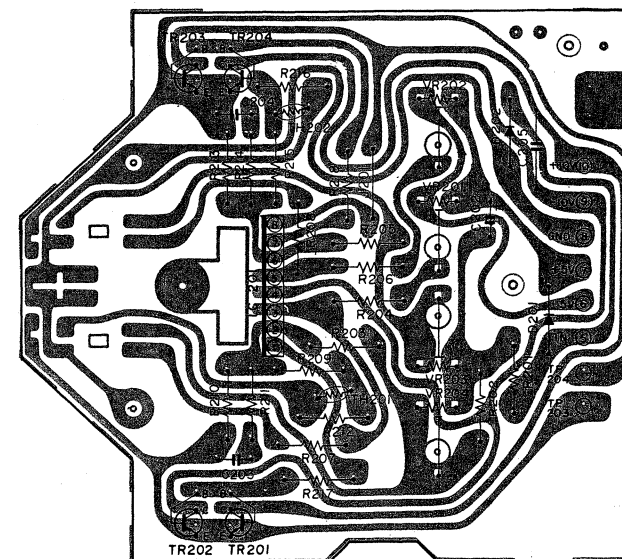


LOCK LED PWB

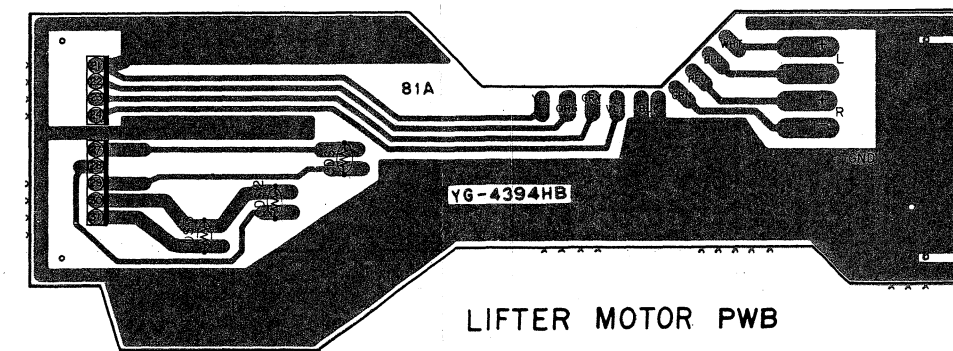


POWER SW.
PWB

KU-441 MOTOR DRIVE UNIT

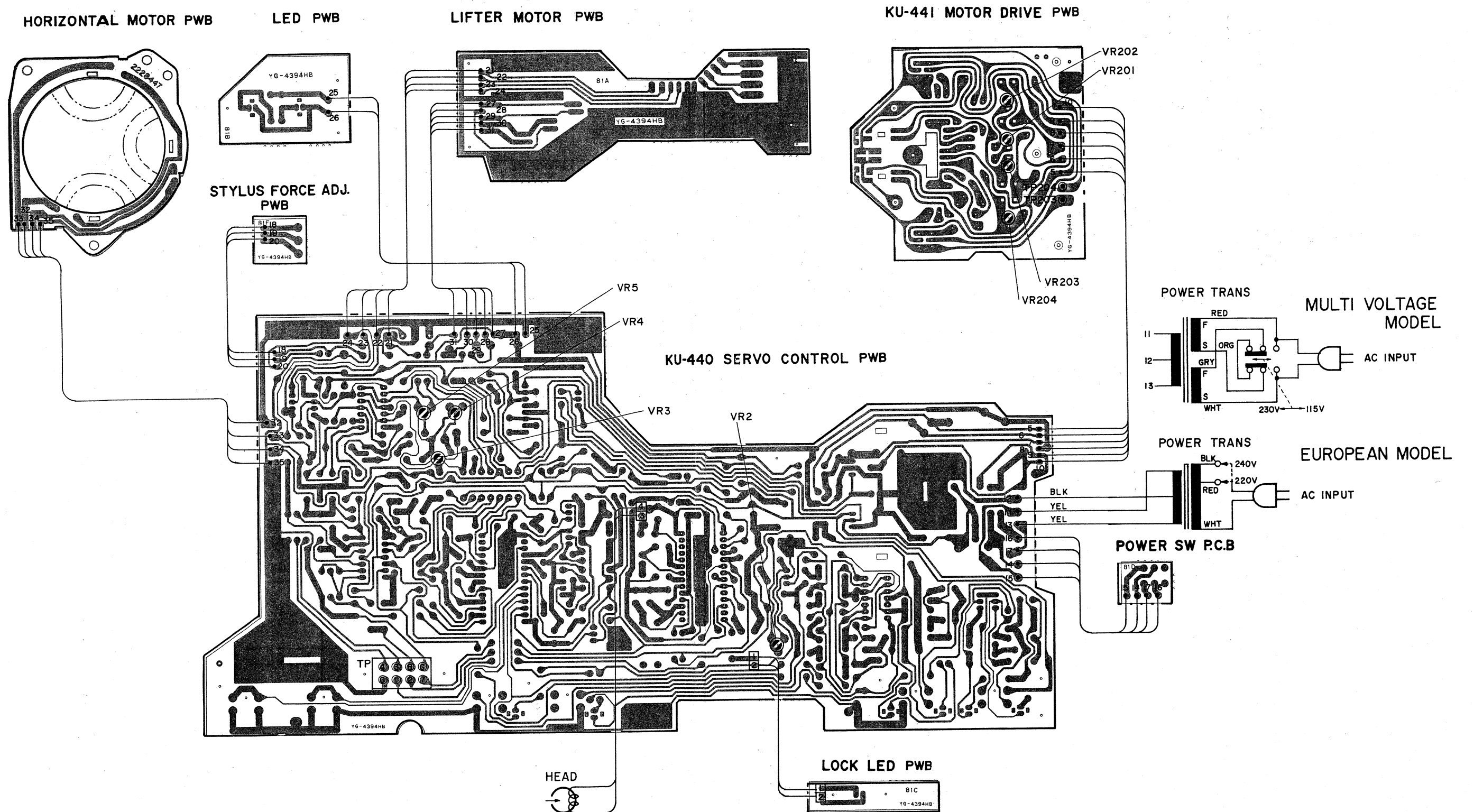


MOTOR DRIVE PWB



LIFTER MOTOR PWB

CONNECTIONS OF P.W. BOARD



PARTS LIST OF P. C. BOARD

KU-440 SERVO CONTROL UNIT

Ref. No.	Part No.	Part Name	Remarks
SEMICONDUCTOR GROUP			
IC8	2620276005	HD14066BP	IC
IC9	2620092001	M53205P	IC
IC1	2630173004	IR3T02	LSI Phonomotor
IC2	2630174003	IR3T03	LSI Tonearm
IC3	2630189001	M5218L	IC
IC4	2630146002	μPC324C	IC
IC5	2630198005	NJM4556	IC
IC6	2630147001	μPC78M05H	IC
IC7	2630160004	μPC7905H	IC
TR1, 2, 10	2710102005	2SA1015(Y)	
TR4~9	2730198002	2SC1815(Y)	
TR3	2740038000	2SD467(C)	
D1~15 } 20~24 }	2760049901	IS2076	
D16~19	2760237001	RV06	
TH1	2760311008	THERMISTOR	
LED1	3939140009	LED (GL-9PG24)	LED
LED2~9	3939041001	LED (LN81RCP(HL))	LED
CdS 2, 3	3939053002	CDS	CDS
CdS 1	3939053028	CDS (10-15KΩ)	CDS
RESISTOR GROUP			
VR6	2118024002	V16V15KB502	Variable resistor 5KΩ
VR2	EP-5462H15	SOLID VOLUME	22KΩ
VR3~5	2116000073	V08PB203	20KΩ
			Metal film
R30	2452195008	RN14K2E332G	3.3KΩ ¼W
R25	2452201002	RN14K2E562G	5.6KΩ ¼W
R113	2452215001	RN14K2E223G	22KΩ ¼W
R115	2452223006	RN14K2E473G	47KΩ ¼W
CAPACITOR GROUP			
C31, 36 38~40 50, 51, 55, 56, 60	2531027000	CK45F1H104Z	Ceramic 0.1μF 50V
C27	2531002009	CK45B1H471K	470PF 50V
C20, 21 46, 52	2531004007	CK45B1H102K	0.001μF 50V
C4	2531008003	CK45B1H472K	0.0047μF 50V
C9, 10	2533619005	CC45SL1H470J	47PF 50V
C54, 57	2533627000	CC45SL1H101J	100PF 50V
C2, 58, 64	2533637003	CC45SL1H271J	270PF 50V
			Electrolitic
C44	2542037005	CE02W1E102=	1000μF 25V
C43	2542038004	CE02W1E222=	2200μF 25V
C33	2544129005	CE04W1A470=	47μF 10V
C8, 30, 34 32, 41, 42 45	2544132005	CE04W1C100=	10μF 16V
C12, 35, 37 49	2544136001	CE04W1C101=	100μF 16V
C24	2544140000	CE04W1V4R7=	4.7μF 35V
C1, 3, 5 18, 61	2544146004	CE04W1H010=	1μF 50V
			Film
C16	2544194017	CQ93P1H473J	0.047μF 50V
C19	2551070008	CQ93M1H682K	0.0068μF 50V
C6, 7, 48	2551072006	CQ93M1H103K	0.01μF 50V
C13, 14, 17 22, 23, 25 26, 28, 29 47	2551122008	CQ93M1H473J	0.047μF 50V

Ref. No.	Part No.	Part Name	Remarks
OTHER PARTS GROUP			
X1	4178028101	HEAT SINK	For IC6, 7
SW1~6	3998025000	CRYSTAL (4.5MHZ)	
SW7	2129130008	PUSH SWITCH	FUNCTION
	2129180003	PUSH SWITCH	POWER
	4438568107	LED HOLDER	For LED2~9

KU-441 MOTOR DRIVE UNIT

Ref. No.	Part No.	Part Name	Remarks
SEMICONDUCTOR GROUP			
IC201	2630189001	M5218L	IC
TR202, 204	2710105002	2SA966(Y)	
TR201, 203	2730201009	2SC2236(Y)	
D201, 202	2760049901	IS2076	
	2760303016	HL-300C	Hall detector
TH201, 202	2760311008	THERMISTOR	TD5-C210D
RESISTOR GROUP			
VR203, 204	2116000031	V08PB102	Variable resistor 1KΩ
VR201, 202	2116000072	V08PB203	20KΩ
CAPACITOR GROUP			
C202	2544132005	CE04W1C100=	Electrolitic 10μF 16V
C203, 204	2551076002	CQ93M1H223K	Film 0.022μF 50V

• The carbon resistors rated at ¼W are not listed herein.